

BEYOND SHAPLEY VALUES

COOPERATIVE GAMES FOR THE INTERPRETATION OF MACHINE LEARNING MODELS

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Institut Intelligence et Données, Université Laval*

Project: *Interpretability of black-box machine learning models*

With Arthur Charpentier (UQÀM), Marie-Pier Côté (ULaval)

Research interests:

Statistical Learning • XAI • Uncertainty Quantification • Sensitivity Analysis • Probability Theory • Cooperative game theory • Functional analysis



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However, **eXplainable AI (XAI) methods** are often backed by **empirical arguments**

“SOTA” methods, testing on limited benchmarks...

This is **not enough** to convince safety/regulatory authorities...

Our position:

Before choosing an XAI method, we need to understand it theoretically

☞ Understand the method before “explaining” the phenomenon

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In this talk:

Revisit **post-hoc model-agnostic** XAI methods based on **cooperative game theory**

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Side quests:

- Understand **what the Shapley values are** and how to go **beyond them**
- Introduce some of **the open questions and challenges** that I will take on during the next two years

Framework and notations

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Let \hat{f} denote the **black-box ML model**, and $\hat{f}(X)$ be the **random output**.

A measurable mapping from E to \mathbb{R} . $\hat{f}(X)$ is a **random variable**.

Remark . We take a **post-hoc, model-agnostic** approach.

“Cooperative game theory = The art of sharing a cake”



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Two ingredients:

- $D = \{1, \dots, d\}$, a **set of players**
The power-set \mathcal{P}_D is the **set of coalitions of players**
- $v : \mathcal{P}_D \rightarrow \mathbb{R}$, a **value function**
It **assigns a value to each coalition**

☞ (D, v) formally defines a **cooperative game**

☞ $v(D)$ is the value of the “grand coalition” (the cake)

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Main concern of the theory of cooperative games:

How can to redistribute $v(D)$ to each of the d players?

A famous example - LMG indices

Example: Lindeman, Merenda, and Gold (1980) indices

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Coalitions: for $A \in \mathcal{P}_D$, the subset of covariates X_A

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Is it possible to aggregate this information (2^d coefficients) into something more manageable?

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It is a mapping $\phi : D \rightarrow \mathbb{R}$, that must ideally respect one criteria:

- **Efficiency:** $\sum_{i \in D} \phi(i) = v(D)$
 - ☞ Ensures that **the we actually redistribute the cake**

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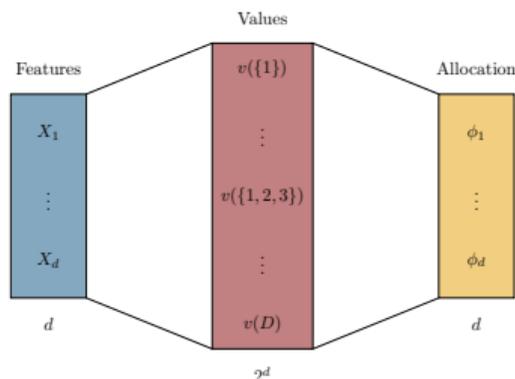
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Value function evaluation

Value function aggregation

In a nutshell:

- Start with a learned model with d input features
- Chose a **value function** resulting in 2^d quantities
- Aggregate the 2^d quantities into d quantities using an **efficient allocation**

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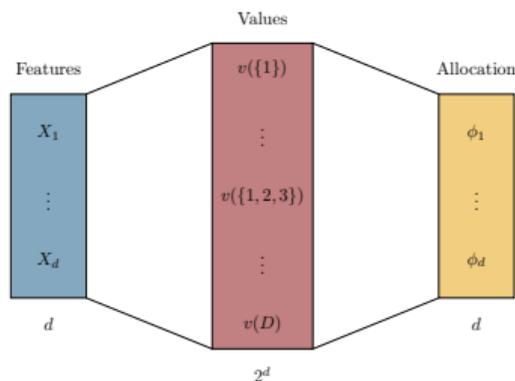
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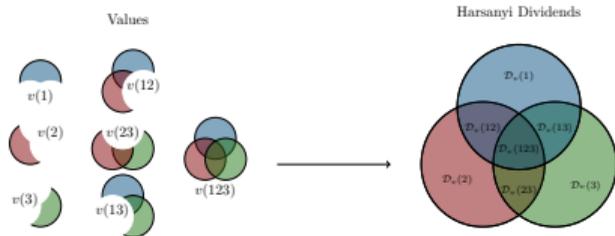
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Is there a way to define efficient **allocations**?

Allocations as a dividend sharing mechanism

The **Harsanyi (1963) dividends** of a cooperative game (D, v) are defined as:

$$\mathcal{D}_v(A) = \sum_{B \in \mathcal{P}_A} (-1)^{|A|-|B|} v(B), \quad \text{or equivalently,} \quad \mathcal{D}_v(A) = v(A) - \sum_{B \in \mathcal{P}_A} \mathcal{D}_v(B)$$



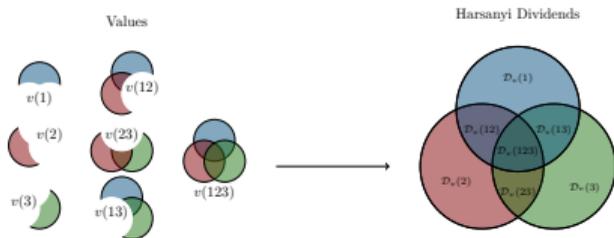
They quantify **the added-value of a coalition**:

$$\mathcal{D}_v(12) = v(12) - v(1) - v(2)$$

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They are the **Möbius inverse** of the **value function**

Proposition (Möbius inversion on power-sets (Rota 1964; Kung, Rota, and Hung Yan 2012)).

For any two set functions $v : \mathcal{P}_D \rightarrow \mathbb{R}$, $\mathcal{D} : \mathcal{P}_D \rightarrow \mathbb{R}$, the following equivalence holds:

$$\forall A \in \mathcal{P}_D, \quad v(A) = \sum_{B \in \mathcal{P}_A} \mathcal{D}(B), \quad \iff \quad \forall A \in \mathcal{P}_D, \quad \mathcal{D}(A) = \sum_{B \in \mathcal{P}_A} (-1)^{|A|-|B|} v(B).$$

(i.e., generalized inclusion-exclusion principle)

Shapley values as the egalitarian dividend sharing mechanism

The **Harsanyi set** is a family of **efficient allocations** that **aggregate of the Harsanyi dividends**:

$$\phi(i) = \sum_{A \in \mathcal{P}_D : i \in A} \lambda_i(A) \mathcal{D}_v(A), \quad \text{where} \quad \begin{cases} \forall i \in D, \forall A \in \mathcal{P}_D, \lambda_i(A) \geq 0, \\ \forall A \in \mathcal{P}_D, \sum_{i \in D} \lambda_i(A) = 1 \end{cases}$$

parametrized by the **weight system** $\lambda : D \times \mathcal{P}_D \rightarrow \mathbb{R}$

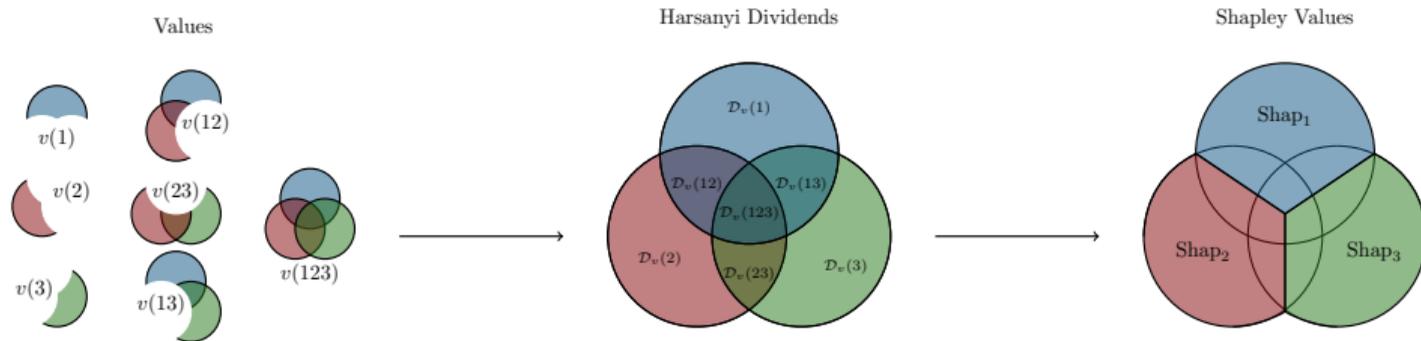
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In this setting, the **Shapley values are the egalitarian redistribution**, i.e., $\lambda_i(A) = 1/|A|$



Allocations using random orders

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The **Weber (1988) set** is a family of **efficient allocations** as an average over the orderings

$$\begin{aligned}\phi(i) &= \mathbb{E}_{\pi \sim p} [v(\{\pi_1, \dots, \pi_{\pi(i)}\}) - v(\{\pi_1, \dots, \pi_{\pi(i)-1}\})] \\ &= \sum_{\pi \in \mathcal{S}_D} p(\pi) [v(\{\pi_1, \dots, \pi_{\pi(i)}\}) - v(\{\pi_1, \dots, \pi_{\pi(i)-1}\})]\end{aligned}$$

parametrized by a **probability mass function** over the permutations \mathcal{S}_D .

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In this setting, the **Shapley values are the uniform distribution over the permutations**, i.e., $p(\pi) = 1/d!$

$$\text{Shap}(i) = \frac{1}{d!} \sum_{\pi \in \mathcal{S}_D} [v(\{\pi_1, \dots, \pi_{\pi(i)}\}) - v(\{\pi_1, \dots, \pi_{\pi(i)-1}\})]$$

The recipe

Overall blueprint for using cooperative games for XAI:

(I., Charpentier, and Fernandes Machado [2025](#))

1. Step 1: Identify a quantity of interest

Choose **a cake worth cutting**, e.g., point predictions $f(x)$, model variance $\mathbb{V}(f(X))\dots$

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And make sure that **$v(D)$ is equal to the quantity of interest**, e.g.,

$\mathbb{E}[f(X) | X_A = x_A]$ for $f(x)$, $\mathbb{V}(\mathbb{E}[f(X) | X_A])$ for $\mathbb{V}(f(X))$...

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3. Step 3: Pick an efficient allocation

In order to summarize the information of the 2^d evaluations of v

☞ Less crucial and can **highlight some model behavior**

**CHALLENGE 1:
CHOOSING A VALUE FUNCTION**

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How do we pick relevant **value functions**?

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A **bad choice** can lead to **misleading insights**

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Conditional expectation

$$v(A) = \mathbb{E}[f(X) \mid X_A = x_A]$$

$$\mathcal{D}_v(\{1\}) = x_1 + \rho(x_1 + x_1^2 - 1) \quad \mathcal{D}_v(\{2\}) = x_2 + \rho(x_2 + x_2^2 - 1)$$

$$\mathcal{D}_v(\{12\}) = x_1x_2 - \rho(x_1 + x_1^2 + x_2 + x_2^2 - 1)$$

$$\text{Shap}_v(\{1\}) = x_1 + \frac{\rho}{2}(x_1 + x_1^2 - x_2 - x_2^2 - 1) + \frac{x_1x_2}{2}$$

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Oblique projections

I. et al. (2025a)

$$\mathcal{D}_v(1) = x_1 \quad \mathcal{D}_v(2) = x_2$$

$$\mathcal{D}_v(12) = x_1x_2$$

$$\text{Shap}_v(\{1\}) = x_1 + \frac{x_1x_2}{2}$$

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Open question: Great contenders, but **we don't know how to estimate them**

**CHALLENGE 2:
PICKING AN ALLOCATION**

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How do we pick a "good" allocation?

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Example: Proportional Marginal Effects (Herin et al. 2024)

- **Quantity of interest**: $\mathbb{V}(f(X))$
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- **Allocation**: *Proportional values*

$$p(\pi) = \frac{L(\pi)}{\sum_{\sigma \in \mathcal{S}_D} L(\sigma)}, \quad L(\pi) = \exp\left(-\sum_{j \in D} \log(v(\{\pi_1, \dots, \pi_{\pi(j)}\}))\right)$$

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Proposition (*Exogeneity detection*).

$$PME_i = 0 \iff X_i \text{ is not in the model.}$$

CHALLENGE 3:
COMPUTATIONAL ASPECTS

Computational aspects - Monte-Carlo type estimates

We need to **evaluate the value function** for the 2^d coalitions

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Proposition (I. et al. 2025b). Let p be a pmf over \mathcal{S}_D . Let $m > 0$ and π_1, \dots, π_m be an i.i.d. sample drawn from p . Assume that $0 < \mathbb{E}_p [(v(\pi^j) - v(\pi^j \setminus \{j\}))^2] < \infty$. Then, for every $j \in D$,

$$\hat{\phi}_v(j) = \frac{1}{m} \sum_{i=1}^m [v(\pi^j) - v(\pi^j \setminus \{j\})],$$

is an unbiased, strongly consistent, and asymptotically normal estimators of $\phi_v(j) := \mathbb{E}_p[h(\pi)]$.

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☞ **Worst-case scenario:** $m \times d$ models to train instead of $d!$.

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Open question: Other types of computational improvement?

Maximal coalition cardinality, parallel and efficient computing, time and memory trade-off...

Quick illustration - Conformal prediction decomposition

Uncertainty attribution based on conformal prediction (CP) intervals:

1. **Quantity of interest:** Width of the CP interval $\widehat{C}(x)$ at point x
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Synthetic model: The Sobol-Levitan function (Sobol' and Levitan 1999)

$$X = (X_1, \dots, X_{16})^\top \sim \mathcal{U}(0, 1)^{\times 16}, \quad \beta \in \mathbb{R}^{16}, \quad \epsilon_Y \sim \mathcal{N}(0, 1), \quad Y = \exp[\beta^\top X] + \prod_{i=1}^{16} \frac{\exp[\beta_i] - 1}{\beta_i} + \epsilon_Y$$

Here, $d = 16$, $d! \approx 2 \times 10^{13}$ and $2^{16} = 65\,536$

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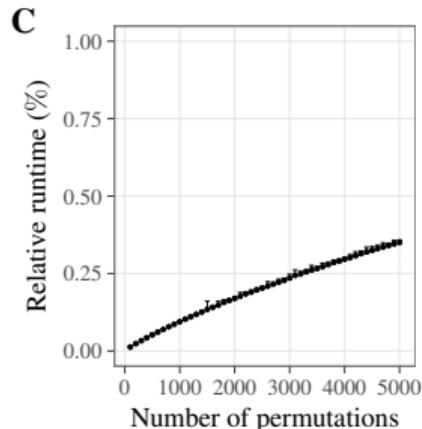
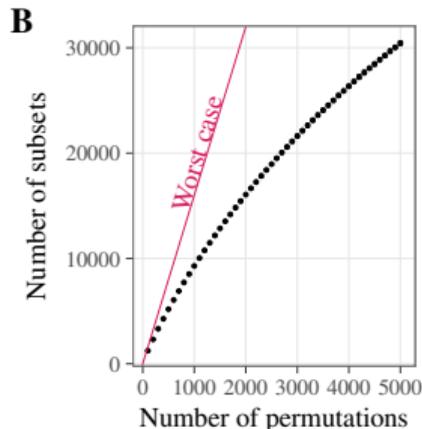
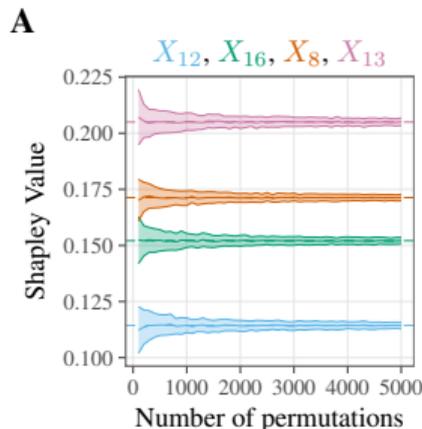
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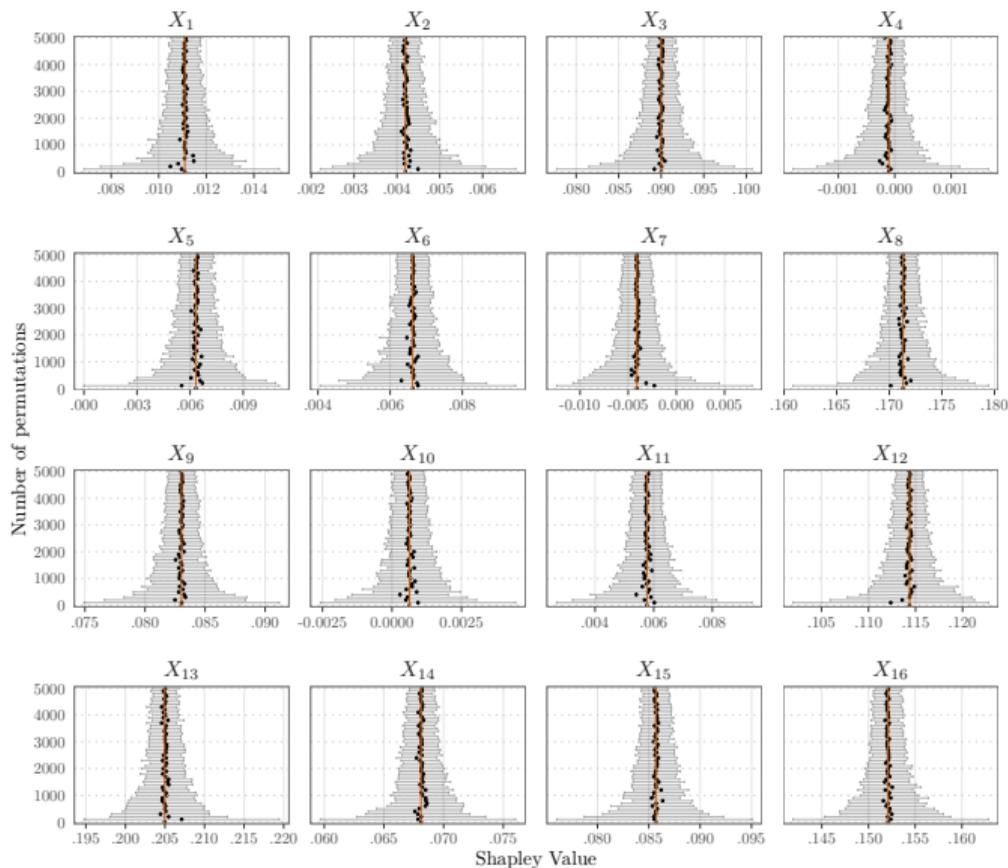
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bike	Bike rental data	17,379	12	Exact
blog	Number of comments per blog posts	52,397	238	$m = 50$
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concrete	Concrete compressive strength	1,030	8	Exact
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More details in our most recent preprint:

Unveil Sources of Uncertainty: Feature Contribution to Conformal Prediction Intervals

Marouane El Idrissi^{a,b,e}, Agathe Fernandes Machado^a, Ewen Gallic^{c,d}, Arthur Charpentier^a

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THANK YOU FOR YOUR ATTENTION!

ANY QUESTIONS?

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